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structure foundations using either the continuous model or the discrete model. This mathematical display is a strong feature of the book as it helps to explain in full detail how calculations are reached and interpreted. In addition to the simple 'uniform' and 'straight' beams, the book introduces solution techniques for the complicated 'non uniform' beams (including linear or non-linear tapered beams), and curved beams. Most of the beams are analyzed by taking account of the effects of shear deformation and rotary inertia of the beams themselves as well as the eccentricities and mass moments of inertia of the attachments. Demonstrates approaches which dramatically cut CPU times to a fraction of conventional FEM Presents "mode shapes" in addition to natural frequencies, which are critical for designers Gives detailed derivations for continuous and discrete model equations of motions Summarizes the analytical and numerical methods for the natural frequencies, mode shapes, and time histories of straight structures rods shafts Euler beams strings Timoshenko beams membranes/thin plates Conical rods and shafts Tapered beams Curved beams Has applications for students taking courses including vibration mechanics, dynamics of structures, and finite element analyses of structures, the transfer matrix method, and Jacobi method This book is ideal for graduate students in mechanical, civil, marine, aeronautical engineering courses as well as advanced undergraduates

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Active touch can be described as the control of the position and movement of tactile sensing systems to facilitate information gain. In other words, it is finding out about the world by reaching out and exploring—sensing by ‘touching’ as opposed to ‘being touched’. In this Research Topic (with cross-posting in both Behavioural Neuroscience and Neurorobotics) we welcomed articles from junior researchers on any aspect of active touch. We were especially interested in articles on the behavioral, physiological and neuronal underpinnings of active touch in a range of species (including humans) for submission to *Frontiers in Behavioural Neuroscience*. We also welcomed articles describing robotic systems with biomimetic or bio-inspired tactile sensing systems for publication in *Frontiers in Neurorobotics*.

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